

## Three Results in Connection with Inverse Matrices

Lothar Berg

*Wilhelm-Pieck-Universität Rostock*

*Sektion Mathematik*

*Universitätsplatz 1*

*Rostock, DDR-2500*

Submitted by Peter Lancaster

---

### ABSTRACT

First we show that the Moore-Penrose solution of an arbitrary system of linear equations is a convex combination of the solutions of all uniquely solvable partial systems. The other two results concern the elements of inverse Toeplitz band matrices, namely the asymptotic behavior of a determinant appearing in a formula of D. S. Meek and a modification of a formula of W. D. Hoskins and P. J. Ponzio for matrices with binomial coefficients in the limit case.

---

### 1. A DETERMINANT REPRESENTATION FOR THE MOORE-PENROSE SOLUTION

Let  $Ax = z$  be a linear system of equations with  $A \in \mathbb{C}^{n,m}$ , and  $x^+ = A^+z$  the corresponding Moore-Penrose solution. According to G. Zielke [23] there exist several generalizations of Cramer's rule to the components of  $x^+$  or, what is equivalent with this, several representations of the elements of  $A^+$  as rational functions of certain determinants with elements from  $A$ , from E. H. Moore [14], to R. Gabriel [10], to J. Springer [16]. Cf. also M. Stojaković [18] and the references cited there, as well as the generalizations by G. C. Verghese [20] and H. J. Werner [21] of a formula of Ben-Israel. Though such formulas have mainly theoretical interest, J. Springer [17] has used their denominator for the foundation of a residue arithmetic to compute the Moore-Penrose inverse exactly. Here we begin with a new proof of one variant of the generalized Cramer's rule.

With this aim we denote the rank of  $A$  by  $r$  and introduce the multiindices

$$p = (p_1, \dots, p_r), \quad q = (q_1, \dots, q_r)$$

with  $1 \leq p_1 < p_2 < \dots < p_r \leq n$  and  $1 \leq q_1 < q_2 < \dots < q_r \leq m$ . The notation  $i \in q$  shall mean that  $q_k = i$  for a certain  $k$ . Further, for  $A = (a_{ij})$  we denote

$${}_p A = (a_{p_i j}) \in \mathbb{C}^{r, m}, \quad A_q = (a_{i q_j}) \in \mathbb{C}^{n, r}, \quad {}_p A_q = (a_{p_i q_j}) \in \mathbb{C}^{r, r},$$

and finally, for a square matrix we use the notation  $|A| = \det A$  for the determinant,  $\|A\| = |\det A|$  for the modulus of the determinant,  $\bar{A} = (\bar{a}_{ij})$ , and  $A_i[z]$  for the matrix  $A$  with its  $i$ th column replaced by the vector  $z$ , the last notation making sense also for rectangular matrices.

**THEOREM 1.** *The  $i$ th component of the Moore-Penrose solution  $x$  of  $Ax = z$  possesses the representation*

$$x_i^+ = \frac{\sum' {}_p \bar{A}_q \|{}_p A_{iq}[{}_p z]\|}{\sum {}_p A_q \|^2}, \quad (1)$$

where the double sums run over all possible multiindices  $p, q$ , but with the prime indicating  $i \in q$  in the numerator sum.

*Proof.* In the case  $n = m = r$  there exists only the trivial possibility  $p = q = (1, \dots, r)$ , so that  ${}_p A_q = A$ , and in view of  $\|A\|^2 = |\bar{A}| |A|$  the formula (1) is just Cramer's rule.

In the general case we can write (cf. G. Zielke [22])

$$A = BC \quad \text{with} \quad B \in \mathbb{C}^{n, r}, \quad C \in \mathbb{C}^{r, m},$$

so that  $A^+ = C^+ B^+$  with  $B^+ = (B^* B)^{-1} B^*$ ,  $C^+ = C^* (C C^*)^{-1}$ . Hence the system  $Ax = z$  splits up into the systems  $By = z$ ,  $Cx = y$ , and we can calculate the Moore-Penrose solutions  $y^+ = B^+ z$ ,  $x^+ = C^+ y^+$  separately. In the special case  $n = m$  we make use of the multiplication theorem (cf. W. I. Smirnow [15])

$$|CB| = \sum_p |C_p| \|{}_p B\|. \quad (2)$$

1. From the representation  $y^+ = (B^*B)^{-1}B^*z$  we find, in view of  $(B^*B)_i[B^*z] = B^*(B_i[z])$  and Cramer's rule,

$$y_i^+ = \frac{|B^*B_i(z)|}{|B^*B|},$$

and according to (2) we obtain

$$y_i^+ = \frac{\sum_p |B_p^*| |B_i[z]|}{|B^*B|}. \quad (3)$$

Using once more (2) with  $C = B^*$  as well as  $|B_p^*| = |\bar{B}_p|$ , we have proved (1) in the special case  $A = B$ , because for  $q$  there exists only the trivial possibility.

2. From  $x^+ = C^*(CC^*)^{-1}y$  we find for the  $i$ th component  $x_i^+ = \bar{c}_i(CC^*)^{-1}y$ , denoting by  $\bar{c}_i$  the vector of the  $i$ th row of  $C^*$ . Applying the identity of Magnus (cf. C. Brezinski [9]), we obtain

$$x_i^+ = -\frac{1}{|CC^*|} \left| \begin{pmatrix} 0 & \bar{c}_i \\ y & CC^* \end{pmatrix} \right|.$$

Now (2) yields

$$\left| \begin{pmatrix} 0 & \bar{c}_i \\ y & CC^* \end{pmatrix} \right| = \left| \begin{pmatrix} 0 & \delta_i \\ y & C \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & C^* \end{pmatrix} \right| = \sum_{q^0} \left| \begin{pmatrix} 0 & \delta_i \\ y & C \end{pmatrix} \right|_{q^0} \left| \begin{pmatrix} 1 & 0 \\ 0 & C^* \end{pmatrix} \right|_{q^0},$$

where  $q^0 = (q_0, q_1, \dots, q_r)$ ,  $0 \leq q_0 < q_1 < \dots < q_r \leq m$ , and  $\delta_i$  denotes the  $i$ th row of the  $r$ -dimensional unit matrix. In the case  $q_0 = 0$  we have

$$\left| \begin{pmatrix} 1 & 0 \\ 0 & C^* \end{pmatrix} \right|_{q^0} = |C^*|;$$

otherwise the determinant on the left-hand side vanishes. In the case  $q_0 = 0$  and  $i \in q^0$  we have

$$\left| \begin{pmatrix} 0 & \delta_i \\ y & C \end{pmatrix} \right|_{q^0} = -|C_{iq}[y]|,$$

whereas in the case  $i \notin q^0$  the matrix on the left-hand side vanishes. Hence we obtain the result

$$x_i^+ = \frac{\sum' |C_{iq}[y]| |{}_q C^*|}{|CC^*|}, \quad (4)$$

where the prime on the sum indicates that there only  $q$  with  $i \in q$  are allowed. In the special case  $A = C$  and  $z = y$  this is, according to (2) with  $B = C^*$ , just (1), because for  $p$  there exists only the trivial possibility.

3. In the general case, since  $x^+ = C^+ y^+$ , we have to substitute (3) into (4) with  $y = y^+$ . Introducing the vector  $z^{(p)}$  with the components  ${}_p B_i[{}_p z]$  for  $i = 1, \dots, r$ , we obtain

$$x_i^+ = \frac{\sum' |B_p^*| |C_{iq}[z^{(p)}]| |{}_q C^*|}{|B^* B| |CC^*|}. \quad (5)$$

Since  ${}_p A_q = ({}_p B)(C_q)$ , we have  ${}_p A_q = |{}_p B| |C_q|$ , so that in view of

$$\sum_{p, q} \|{}_p A_q\|^2 = \sum_p \|{}_p B\|^2 \sum_q \|C_q\|^2 \quad (6)$$

and (2), the denominator of (5) equals the denominator of (1). In the regular case the formula  $({}_p A_q)^{-1} = (C_q)^{-1}({}_p B)^{-1}$  implies, by Cramer's rule,  ${}_p A_{iq}[{}_p z] = C_{iq}[z^{(p)}]$ , and by continuity arguments this result must also be valid in the singular case. Hence in view of  $|{}_p \bar{A}_q| = |{}_q A_p^*| = |{}_q C^*| |B_p^*|$ , Equation (5) goes over into (1), and the theorem is proved. ■

REMARKS. The double sum in the numerator of (1) contains  $\binom{n}{r}$  terms in  $p$  and  $\binom{m-1}{r-1}$  terms in  $q$ , i.e. altogether

$$\binom{n}{r} \binom{m-1}{r-1}$$

terms. The double sum in the denominator contains

$$\binom{n}{r} \binom{m}{r}$$

terms.

To *interpret* the result we introduce the notations

$$\beta = \sum_p \| {}_p B \|^2, \quad \beta_p = \frac{1}{\beta} \| {}_p B \|^2, \quad \gamma = \sum_q \| C_q \|^2, \quad \gamma_q = \frac{1}{\gamma} \| C_q \|^2.$$

In the case  $| {}_p A_q | \neq 0$  let  $x^{(p,q)}$  be the canonical imbedding of the solution of  ${}_p A_q x = {}_p z$  into the  $m$ -dimensional space, this means that  $x^{(p,q)}$  possesses according to Cramer's rule the components

$$x_i^{(p,q)} = \frac{| {}_p A_{iq} [ {}_p z ] |}{| {}_p A_q |}$$

for  $i \in q$ , and  $x_i^{(p,q)} = 0$  otherwise. In the singular case we define  $x^{(p,q)}$  to be the zero vector. Now in view of (5) and (6) we can write (1) in the form

$$x_i^+ = \sum'_{p,q} \beta_p \gamma_q x_i^{(p,q)}. \quad (7)$$

The definition of  $x^{(p,q)}$  in the singular case  $| {}_p A_q | = 0$  does not influence the components (7) in view of  $\beta_p \gamma_q = 0$ . Since

$$\sum_p \beta_p = 1, \quad \sum_q \gamma_q = 1,$$

we obtain from (7) the

**COROLLARY.** *The Moore-Penrose solution  $x^+$  of the linear system  $Ax = z$  is the convex combination*

$$x^+ = \sum_{p,q} \beta_p \gamma_q x^{(p,q)} \quad (8)$$

*of the solutions of all uniquely solvable  $r$ -dimensional subsystems canonically imbedded into  $\mathbb{C}^m$ .*

Note that the sum in (8) has, in contrast to (7), no prime. In the case  $m = r$  with trivial  $q$  and  $\gamma_q = 1$ , where we can put  $C = I$ , i.e.  $A = B$ , the components (7) can be interpreted as the *least-squares solutions of the linear systems*

$$| {}_p A | x_i = | {}_p A_i [ {}_p z ] |$$

for all  $p$ , but a fixed  $i$ .

## 2. TOEPLITZ MATRICES

In this paragraph we summarize some notation and results needed later on. A square Toeplitz matrix  $A \in \mathbb{C}^{n,n}$  possesses the structure

$$A = \begin{pmatrix} a_0 & a_{-1} & \cdots & a_{-p} & & \bigcirc \\ a_1 & a_0 & \cdot & & \ddots & \\ \vdots & \cdot & \cdot & \cdot & & a_{-p} \\ a_q & & \cdot & \cdot & \cdot & \vdots \\ & \ddots & & \cdot & a_0 & a_{-1} \\ \bigcirc & & a_q & \cdots & a_1 & a_0 \end{pmatrix}. \quad (9)$$

We assume  $1 \leq p, q < n$  and  $a_{-p}a_q \neq 0$ . Generally speaking,  $A$  is a band matrix, though the case  $p = q = n - 1$  is allowed. Because of their simple shape and their importance for many applications, there exists an extensive literature on these matrices, from which we cite only A. Böttcher and B. Silbermann [8], G. Heinig and K. Rost [11], and L. Berg [5].

The linear system  $Ax = z$  is equivalent to the difference equation

$$a_{-p}x_{i+p} + \cdots + a_0x_i + \cdots + a_qx_{i-q} = z_i \quad (10)$$

for  $i = 1, \dots, n$  under the boundary conditions

$$x_0 = x_{-1} = \cdots = x_{1-q} = 0, \quad x_{n+1} = \cdots = x_{n+p} = 0. \quad (11)$$

Let  $h_i$  be the solution of the homogeneous equation belonging to (10) under the initial conditions

$$h_p = 1/a_{-p}, \quad h_i = 0 \quad \text{for } i < p. \quad (12)$$

Then the *two-sided infinite Toeplitz matrix*  $H = (h_{i-j})$ ,  $-\infty < i, j < \infty$ , is an inverse of the two-sided infinite matrix corresponding to (9). Let

$$a_{-p}\lambda^{p+q} + \cdots + a_0\lambda^q + \cdots + a_q \quad (13)$$

be the characteristic polynomial of (10), and  $\lambda_{-r}, \dots, \lambda_s$  the pairwise differ-

ent zeros of (13) with the multiplicities  $k_{-r}, \dots, k_s$  such that  $k_{-r} + \dots + k_s = p + q$ . Then  $h_i$  possesses for  $i > -q$  the representation

$$h_i = \sum_{\rho = -r}^s P_{\rho}(i) \lambda_{\rho}^i, \quad (14)$$

which can be constructed with the help of operational calculus, where the coefficients  $P_{\rho}(i)$  are polynomials in  $i$  with the exact degree  $k_{\rho} - 1$ .

Now we assume that  $A \in \mathbb{C}^{n,n}$  is regular, and we introduce the *inverse matrix*  $A^{-1} = (d_{ij})$ ,  $i, j = 1, \dots, n$ . Among several well-known explicit formulas for the elements  $d_{ij}$  we only mention the recent formula of D. S. Meek [13] (cf. also L. Berg [4])

$$d_{ij} = \frac{1}{\Delta_n} \begin{vmatrix} h_{i-j} & h_{n+1-j} & \cdots & h_{n+p-j} \\ h_i & h_{n+1} & \cdots & h_{n+p} \\ \vdots & \vdots & & \vdots \\ h_{i+p-1} & h_{n+p} & \cdots & h_{n+2p-1} \end{vmatrix}, \quad (15)$$

$$\Delta_n = \begin{vmatrix} h_{n+1} & h_{n+2} & \cdots & h_{n+p} \\ h_{n+2} & h_{n+3} & \cdots & h_{n+p+1} \\ \vdots & \vdots & & \vdots \\ h_{n+p} & h_{n+p+1} & \cdots & h_{n+2p-1} \end{vmatrix}.$$

For the determinant of  $A$  there is an explicit formula by W. F. Trench [19] (cf. also L. Berg [6]).

Finally, we consider the *one-sided infinite matrix*  $A = (a_{i-j})$ ,  $1 \leq i, j < \infty$ , with  $a_i = 0$  for  $i > q$  and  $i < -p$  corresponding to (9) under the condition

$$|\lambda_{-r}| \leq \dots \leq |\lambda_0| < |\lambda_1| \leq \dots \leq |\lambda_s| \quad (16)$$

with  $k_{-r} + \dots + k_0 = q$ ,  $k_1 + \dots + k_s = p$ . Then operational calculus provides an inverse matrix  $G = (g_{ij})$  of  $A$  with the elements

$$g_{ij} = \sum_{\rho = -r}^0 \sum_{\mu = 0}^{k_{\rho}-1} b_{\rho\mu} \sum_{\sigma = 1}^s \sum_{\nu = 0}^{k_{\sigma}-1} c_{\sigma\nu} G_{ij}^{(\mu, \nu)}(\lambda_{\rho}, \lambda_{\sigma}), \quad (17)$$

where  $b_{\rho\mu}, c_{\sigma\nu}$  are the coefficients of the decompositions into partial fractions

$$\lambda^{q-1} \prod_{\rho=-r}^0 (\lambda - \lambda_\rho)^{-k_\rho} = \sum_{\rho=-r}^0 \sum_{\mu=0}^{k_\rho-1} \frac{\lambda^\mu b_{\rho\mu}}{(\lambda - \lambda_\rho)^{\mu+1}}, \quad (18)$$

$$a_{-p} \prod_{\sigma=1}^s (\lambda - \lambda_\sigma)^{-k_\sigma} = \sum_{\sigma=1}^s \sum_{\nu=0}^{k_\sigma-1} \frac{c_{\sigma\nu}}{(\lambda - \lambda_\sigma)^{\nu+1}},$$

and where

$$G_{ij}^{(\mu, \nu)}(\alpha, \beta) = \frac{1}{\mu! \nu!} \frac{\partial^{\mu+\nu}}{\partial \alpha^\mu \partial \beta^\nu} \frac{1}{\beta - \alpha} \\ \times \begin{cases} (\alpha^{i+\mu} \beta^{-j} - \alpha^\mu \beta^{i-j}) & \text{for } i \leq j, \\ (\alpha^{i+\mu} \beta^{-j} - \alpha^{i+\mu-j}) & \text{for } i \geq j. \end{cases} \quad (19)$$

### 3. THE ASYMPTOTIC BEHAVIOR OF MEEK'S DETERMINANT

The knowledge of the asymptotic behavior of inverse Toeplitz matrices for  $n \rightarrow \infty$  is useful for the estimation of the numerical stability of large linear systems with such matrices [5]. Another application of these asymptotics is the construction of holomorphic solutions of partial differential equations [1], [7]. Here we only deal with Meek's determinant  $\Delta_n$  from (15). At the end of this section we make some remarks concerning the elements  $d_{ij}$ .

We introduce the generalized Vandermonde matrix

$$V(\lambda) = (\lambda^i j^{j-1}) = \begin{pmatrix} \lambda & \lambda & \dots & \lambda \\ \lambda^2 & 2\lambda^2 & \dots & 2^{k-1}\lambda^2 \\ \vdots & \vdots & & \vdots \\ \lambda^p & p\lambda^p & \dots & p^{k-1}\lambda^p \end{pmatrix}$$

with  $i = 1, \dots, p$  and  $j = 1, \dots, k$ , and the square matrix

$$Q(\lambda) = \left( \frac{1}{(i-1)!(j-1)!} P^{(i+j-2)}(n) \lambda^n \right) \quad (20)$$



with  $i, j = 1, \dots, k$ . Then for a polynomial  $P(n)$  of degree  $k-1$ , Taylor's expansion

$$P(n+i+j)\lambda^{n+i+j} = \sum_{\nu, \mu=1}^k \lambda^i i^{\nu-1} \frac{1}{(\nu-1)!(\mu-1)!} P^{(\nu+\mu-2)}(n) \lambda^{n+j} j^{\mu-1}$$

is equivalent to the matrix equation

$$(P(n+i+j)\lambda^{n+i+j}) = V(\lambda)Q(\lambda)V^T(\lambda)$$

with  $i, j = 1, \dots, p$ . According to (14) we have

$$(h_{n+i+j}) = \left( \sum_{\rho=-r}^s P_{\rho}(n+i+j)\lambda_{\rho}^{n+i+j} \right).$$

With the notation  $V_{\rho} = V(\lambda_{\rho})$  with  $k = k_{\rho}$ ,  $Q_{\rho} = Q(\lambda_{\rho})$  with  $P(n) = P_{\rho}(n)$ , and the block matrices  $V = (V_s, \dots, V_{-r}) \in \mathbb{C}^{p, p+q}$ ,  $Q = \text{diag}(Q_s, \dots, Q_{-r}) \in \mathbb{C}^{p+q, p+q}$ , this equation reads

$$(h_{n+i+j}) = VQV^T. \quad (21)$$

**THEOREM 2.** *Under the assumption (16) with  $k_1 + \dots + k_s = p$ , one has the asymptotic representation*

$$\Delta_n \sim \delta(\lambda_s^{k_s} \dots \lambda_1^{k_1})^n \quad (22)$$

for  $n \rightarrow \infty$  with a certain constant  $\delta \neq 0$ .

*Proof.* The matrix  $Q(\lambda)$  from (20) possesses on the secondary diagonal  $i+j = k+1$  the elements

$$\frac{1}{(i-1)!(j-1)!} P^{(k-1)}(n) \lambda^n$$

and below this diagonal only zero elements. Since  $P^{(k-1)}(n)$  is a constant independent of  $n$ , we find for the determinant of  $Q(\lambda)$  the form

$$|Q(\lambda)| = \gamma \lambda^{kn}$$

with  $\gamma \neq 0$ . From (15) and (21) we obtain

$$\Delta_{n+1} = |VQV^T|,$$

and this determinant does not change its value if we add to the rows of  $V$  linear combinations of the other rows of  $V$ . By such manipulations we can transform  $V$  into a matrix  $\tilde{V}$  with zero elements below the main diagonal. Since  $\tilde{V} \in \mathbb{C}^{p, p+q}$  and  $k_1 + \dots + k_s = p$ , this means that in the corresponding block representation  $\tilde{V} = (\tilde{V}_s, \dots, \tilde{V}_1, \tilde{V}_0, \dots, \tilde{V}_{-r})$  the partial matrix  $(\tilde{V}_s, \dots, \tilde{V}_1)$  is a square upper triangular matrix with a determinant different from zero, since  $|V_s, \dots, V_1|$  is a generalized Vandermonde. Now it is easily seen that for  $n \rightarrow \infty$

$$\begin{aligned} \Delta_{n+1} &= |\tilde{V}Q\tilde{V}^T| \sim |V_s, \dots, V_1|^2 |\text{diag}(Q_s, \dots, Q_1)| \\ &= \delta(\lambda_s^{k_s} \dots \lambda_1^{k_1})^{n+1}, \end{aligned}$$

since the elements of  $Q_0, \dots, Q_{-r}$  possess, in view of (16) and (20), a lower order than the other elements. Hence the assertion (22) is proved. ■

Now we consider the case

$$|\lambda_{-r}| \leq \dots \leq |\lambda_0| < |\lambda_1| = \dots = |\lambda_t| < |\lambda_{t+1}| \leq \dots \leq |\lambda_s|$$

with

$$p = l + k_{t+1} + \dots + k_s, \quad 1 \leq l < k_1 + \dots + k_t$$

and  $k_1 \leq k_2 \leq \dots \leq k_t$ . The quadratic form

$$R = \sum_{\rho=1}^t (k_\rho - \beta_\rho) \beta_\rho \quad (23)$$

may have a unique maximum for integer variables  $\beta_\rho$  under the conditions  $0 \leq \beta_\rho \leq k_\rho$  and

$$\beta_1 + \dots + \beta_t = l.$$

The explicit solution of this *quadratic optimization problem* is given in [3].

**THEOREM 3.** *Under the assumptions just mentioned one has the asymptotic representation*

$$\Delta_n \sim \delta n^R (\lambda_1^{\beta_1} \dots \lambda_t^{\beta_t} \lambda_{t+1}^{k_{t+1}} \dots \lambda_s^{k_s})^n \quad (24)$$

for  $n \rightarrow \infty$  with a certain constant  $\delta \neq 0$ , where  $\beta_1, \dots, \beta_t$  is the solution of the optimization problem and  $R$  the corresponding maximal value of (23).

*Proof.* We only sketch the changes to the foregoing proof. For  $\rho = 1, \dots, t$  we consider the block decomposition

$$Q_\rho = \begin{pmatrix} X_\rho & W_\rho \\ U_\rho & Z_\rho \end{pmatrix}$$

with  $X_\rho \in \mathbb{C}^{\beta_\rho \times \beta_\rho}$ ,  $Z_\rho \in \mathbb{C}^{k_\rho - \beta_\rho \times k_\rho - \beta_\rho}$ , and substitute in  $Q$  the partial block  $\text{diag}(Q_t, \dots, Q_1)$  by the rearrangement

$$\begin{pmatrix} X & W \\ U & Z \end{pmatrix}$$

with  $X = \text{diag}(X_t, \dots, X_1)$  and analogous definitions of  $U, W, Z$ . Analogously, we split up  $V_i = (V_i^+, V_i^-)$ , where  $V_i^+$  consists of the  $\beta_i$  first and  $V_i^-$  of the  $k_i - \beta_i$  last columns of  $V_i$ , and rearrange  $V$  as  $(V_s, \dots, V_{t+1}, V_t^+, \dots, V_1^+, V_t^-, \dots, V_1^-, V_0, \dots, V_{-r})$ . Then it follows as before that

$$\Delta_{n+1} \sim |V_s, \dots, V_{t+1}, V_t^+, \dots, V_1^+|^2 |\text{diag}(Q_s, \dots, Q_{t+1}, X_t, \dots, X_1)|$$

and from this, since

$$|X_\rho| = \gamma_\rho n^{(k_\rho - \beta_\rho)\beta_\rho} \lambda_\rho^{\beta_\rho n}$$

with  $\gamma_\rho \neq 0$ , we have the assertion (24). ■

**REMARKS.** Under the assumptions of Theorem 2 we expect

$$d_{ij} = \begin{cases} O((j-i+p)^{k_+-1} \lambda_1^{i-j}) & \text{for } i < j+p, \\ O((i-j+q)^{k_--1} \lambda_0^{i-j}) & \text{for } i > j-q \end{cases} \quad (25)$$

uniformly for  $1 \leq i, j \leq n$  and  $n \rightarrow \infty$ , with  $k_+ = \max k_\rho$  for  $|\lambda_\rho| = |\lambda_1|$  and  $k_- = \max k_\rho$  for  $|\lambda_\rho| = |\lambda_0|$ . Under the assumptions of Theorem 3 we have according to [3]

$$d_{ij} = O((i \wedge j) i^{k_i - \beta_i - 1} j^{\beta_j - 1} \lambda_1^{i-j})$$

uniformly for  $1 \leq i, j \leq n$  and  $n \rightarrow \infty$  with  $i \wedge j = \min(i, j)$ . There exist

examples in which the last estimation can be sharpened to

$$d_{ij} = O\left((i \wedge j) i^{k_t - \beta_t - 1} j^{\beta_t - 1} \left(1 - \frac{i \wedge j}{n+1}\right) \times \left(1 - \frac{i}{n+1}\right)^{\beta_t - 1} \left(1 - \frac{j}{n+1}\right)^{k_t - \beta_t - 1} \lambda_1^{i-j}\right), \quad (26)$$

but a general proof of (25) and (26) is still to be found.

#### 4. THE INVERSE OF A TOEPLITZ MATRIX WITH BINOMIAL COEFFICIENTS

First we generalize (19) to the case  $\alpha = \beta$ . For this purpose we write (19) in the form

$$G_{ij}^{(\mu, \nu)}(\alpha, \beta) = \varepsilon \frac{1}{\mu! \nu!} \frac{\partial^{\mu+\nu}}{\partial \alpha^\mu \partial \beta^\nu} \alpha^k \beta^l \frac{\beta^m - \alpha^m}{\beta - \alpha}$$

with  $k = \mu$ ,  $l = -j$ ,  $m = i$ ,  $\varepsilon = -1$  for  $i \leq j$ , and  $k = i + \mu$ ,  $l = 0$ ,  $m = -j$ ,  $\varepsilon = 1$  for  $i \geq j$  or, what is the same,

$$G_{ij}^{(\mu, \nu)}(\alpha, \beta) = \frac{\varepsilon m}{\mu! \nu!} \frac{\partial^{\mu+\nu}}{\partial \alpha^\mu \partial \beta^\nu} \alpha^k \beta^l \int_0^1 [\alpha + (\beta - \alpha)u]^{m-1} du.$$

Applying the Leibniz formula, we obtain

$$G_{ij}^{(\mu, \nu)}(\alpha, \beta) = \frac{\varepsilon m}{\mu! \nu!} \sum_{\rho=0}^{\mu} \sum_{\sigma=0}^{\nu} \binom{\mu}{\rho} \binom{\nu}{\sigma} (k)_{\mu-\rho} \alpha^{k-\mu+\rho} (l)_{\nu-\sigma} \beta^{l-\nu+\sigma} \times (m-1)_{\rho+\sigma} \int_0^1 [\alpha + (\beta - \alpha)u]^{m-\rho-\sigma-1} (1-u)^\rho u^\sigma du$$

with  $(k)_{\mu-\rho} = k(k-1) \cdots (k-\mu+\rho+1)$  and analogous expressions in the other cases. For  $\alpha = \beta$  we find, since  $k + l + m = \mu + i - j$ ,

$$G_{ij}^{(\mu, \nu)}(\beta, \beta) = \varepsilon \beta^{i-j-\nu-1} \sum_{\rho=0}^{\mu} \sum_{\sigma=0}^{\nu} \binom{k}{\mu-\rho} \binom{l}{\nu-\sigma} \binom{m}{\rho+\sigma+1}.$$

According to the elementary formula

$$\sum_{\rho=0}^{\mu} \binom{\mu}{\rho} \binom{i}{\rho + \sigma + 1} = \binom{i + \mu}{\mu + \sigma + 1}$$

we have therefore the result

$$G_{ij}^{(\mu, \nu)}(\beta, \beta) = \begin{cases} \beta^{i-j-\nu-1} \sum_{\sigma=0}^{\nu} (-1)^{\nu+\sigma+1} \binom{j+\nu-\sigma-1}{\nu-\sigma} \binom{i+\mu}{\mu+\sigma+1} & \text{for } i \leq j, \\ \beta^{i-j-\nu-1} \sum_{\rho=0}^{\mu} (-1)^{\nu+\rho+1} \binom{j+\nu+\rho}{\nu+\rho+1} \binom{i+\mu}{\mu-\rho} & \text{for } i \geq j. \end{cases} \quad (27)$$

The formula (27) possesses a *symmetry property*. To prove this we denote the sums in (27) by  $G_{ijk}^{(\mu, \nu)}$  with  $k=1$  in the first and  $k=2$  in the second case, and consider the generating function

$$\sum_{i=1}^{\infty} G_{ij1}^{(\mu, \nu)} u^{i-1} = \sum_{\sigma=0}^{\nu} (-1)^{\nu+\sigma+1} \binom{j+\nu-\sigma-1}{\nu-\sigma} \frac{u^{\sigma}}{(1-u)^{\mu+\sigma+2}}.$$

In view of the fact that

$$\left( \frac{u}{1-u} \right)^{\sigma} = \left( \frac{1}{1-u} - 1 \right)^{\sigma} = \sum_{\rho=0}^{\sigma} \binom{\sigma}{\rho} \frac{(-1)^{\sigma+\rho}}{(1-u)^{\rho}}$$

and the elementary formula

$$\sum_{\sigma=\rho}^{\nu} \binom{j+\nu-\sigma-1}{\nu-\sigma} \binom{\sigma}{\rho} = \binom{j+\nu}{\nu-\rho},$$

we find

$$\begin{aligned} \sum_{i=1}^{\infty} G_{ij1}^{(\mu, \nu)} u^{i-1} &= \sum_{\rho=0}^{\nu} (-1)^{\nu+\rho+1} \binom{j+\nu}{\nu-\rho} \frac{1}{(1-u)^{\mu+\rho+2}} \\ &= \sum_{i=1}^{\infty} (-1)^{\mu+\nu} (-1)^{\mu+\nu} G_{ji2}^{(\nu, \mu)} u^{i-1} \end{aligned}$$

and therefore obtain the desired identity

$$(-1)^\mu G_{ij}^{(\mu, \nu)}(1, 1) = (-1)^\nu G_{ji}^{(\nu, \mu)}(1, 1). \quad (28)$$

A concrete example is

$$T = \left( (-1)^{i+j+p} \binom{p+q}{i-j+p} \right) \quad (29)$$

with  $i, j = 1, 2, \dots$ . In this case we consider the polynomial  $(\lambda - 1)^{p+q}$  from (13) as the limit case of  $(\lambda - \lambda_1)^p (\lambda - \lambda_0)^q$  for  $\lambda_0 \rightarrow \lambda_1 = 1$ . Hence in (18) we have  $r = 0$ ,  $k_0 = q$ ,  $s = 1$ ,  $k_1 = p$ , and  $b_{0, q-1} = c_{1, p-1} = 1$  with  $b_{0\mu} = b_{1\nu} = 0$  otherwise, and the formula (17) for the elements of an inverse matrix of (29) implies

$$g_{ij} = G_{ij}^{(q-1, p-1)}(1, 1). \quad (30)$$

Let us mention that W. D. Hoskins and P. J. Ponzo [12] have given a formula in the case  $p = q$  for the elements of the inverse of  $T$  in the  $n$ -dimensional case, which for  $n \rightarrow \infty$  converges to

$$g_{ij} = \binom{i}{p} \sum_{k=0}^{p-1} (-1)^{k+1} \binom{p}{k} \binom{j+k+p-1}{2p-1} \frac{p-k}{i+k}$$

for  $i \geq j$  and  $g_{ji} = g_{ij}$ . Other representations may be found in [2]. But all these formulas are less convenient than the representation (30) with (27).

## REFERENCES

- 1 L. Berg, Asymptotische Abschätzung inverser Matrizen mit einer Anwendung auf partielle Differentialgleichungen, *Z. Angew. Math. Mech.* 60:453–458 (1980).
- 2 L. Berg, Die Invertierung von Matrizen aus Binomialkoeffizienten, *Z. Angew. Math. Mech.* 63:639–642 (1983).
- 3 L. Berg, Asymptotische Abschätzung der Inversen Toeplitzscher Bandmatrizen im Grenzfall, *Z. Anal. Anwendungen* 3:179–191 (1984).
- 4 L. Berg, Über die Greensche Funktion und die reduzierte Wronskische Determinante, *Rostock. Math. Kolloq.* 26:45–50 (1984).
- 5 L. Berg, Lineare Gleichungssysteme mit Bandstruktur und ihr asymptotisches Verhalten, VEB DVW, Berlin, to appear.

- 6 L. Berg, Über eine Identität von W. F. Trench zwischen der Toeplitzschen und einer verallgemeinerten Vandermondeschen Determinante, *Z. Angew. Math. Mech.* 66:314–315 (1986).
- 7 L. Berg, On the majorization method for holomorphic solutions of linear partial differential equations, *Z. Anal. Anwendungen* 5:111–117 (1986).
- 8 A. Böttcher and B. Silbermann, Invertibility and Asymptotics of Toeplitz Matrices, *Math. Res.* 17, Akademie, Berlin, 1983.
- 9 C. Brezinski, Some determinantal identities in a vector space with applications, in *Lecture Notes in Math.* 1071:1–11, Springer, New York, 1984.
- 10 R. Gabriel, Pseudoinversen mit Schlüssel und ein System der algebraischen Kryptographie, *Rev. Roumaine Math. Pures Appl.* 22:1077–1099 (1977).
- 11 G. Heinig and K. Rost, Algebraic Methods for Toeplitz-like Matrices and Operators, *Math. Res.* 19, Akademie, Berlin, 1984.
- 12 W. D. Hoskins and P. J. Ponzio, Some properties of a class of band matrices, *Math. Comp.* 26:393–400 (1972).
- 13 D. S. Meek, The inverses of Toeplitz band matrices, *Linear Algebra Appl.* 49:117–129 (1983).
- 14 E. H. Moore, On the reciprocal of the general algebraic matrix, Abstract, *Bull. Amer. Math. Soc.* 26:394–395 (1920).
- 15 W. I. Smirnow, Lehrgang der höheren Mathematik III, 1 (transl. from Russian), VEB DVW, Berlin, 1981.
- 16 J. Springer, Exakte Rechnung durch Residuenarithmetik und einige Möglichkeiten ihrer Anwendung, Dissertation A, Martin-Luther-Universität Halle-Wittenberg, Halle, 1982.
- 17 J. Springer, Die exakte Berechnung der Moore-Penrose-Inversen einer Matrix durch Residuenarithmetik, *Z. Angew. Math. Mech.* 63:203–210 (1983).
- 18 M. Stojaković, Generalized inverse matrices, in *Mathematical Structures — Computational Mathematics — Mathematical Modelling*, Sofia, 1975, pp. 461–470.
- 19 W. F. Trench, On the eigenvalue problem for Toeplitz band matrices, *Linear Algebra Appl.* 64:199–214 (1985).
- 20 G. C. Verghese, A “Cramer rule” for the least-norm, least-squared-error solution of inconsistent linear equations, *Linear Algebra Appl.* 48:315–316 (1982).
- 21 H. J. Werner, On extensions of Cramer’s rule for solutions of restricted linear systems, *Linear and Multilinear Algebra* 15:319–330 (1984).
- 22 G. Zielke, Verallgemeinerte inverse Matrizen, in *Jahrbuch Überblicke Math.* BI, Mannheim, 1983, pp. 95–116.
- 23 G. Zielke, Private communication, 3 Mar. 1985.

Received 19 April 1985; revised 30 July 1985